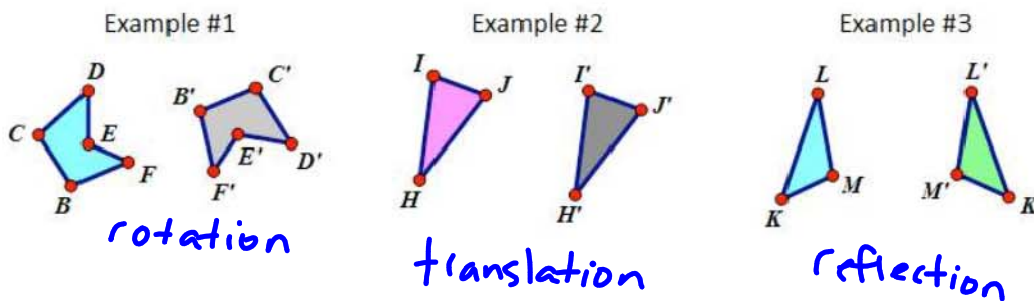


Geometry CC – Mr. Valentino
 Unit 4 Lesson 8: Identifying Compositions

Name: _____
 Date: _____ Period: _____

It is important to take some time to identify the properties of the images that are being rotated, reflected, translated, or a combination of the three.

An ISOMETRY (RIGID MOTION) is a transformation that preserves the distances and/or angles between the pre-image and image.



Definition: orientation (lettering): The lettering of the points of the pre-image, in this diagram, is clockwise A-B-C, while the image is lettered counterclockwise A'-B'-C'. When lettering changes direction, in this manner, the transformation is referred to as a non-direct or opposite isometry.

Properties preserved under a line reflection from the pre-image to the image.

1. distance (lengths of segments remain the same)
2. angle measures (remain the same)
3. parallelism (parallel lines remain parallel)
4. collinearity (points remain on the same lines)

The **orientation** (lettering around the outside of the figure), is **not preserved**. The order of the lettering in a reflection is reversed (from clockwise to counterclockwise or vice versa).

Direct isometry → orientation is preserved
 Opposite isometry → orientation is NOT preserved

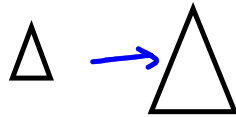
Properties preserved under a translation from the pre-image to the image.

1. **distance** (lengths of segments remain the same)
2. **angle measures** (remain the same)
3. **parallelism** (parallel lines remain parallel)
4. **collinearity** (points remain on the same lines)
5. **orientation** (lettering order remains the same)

Properties preserved under a rotation from the pre-image to the image.

1. **distance** (lengths of segments remain the same)
2. **angle measures** (remain the same)
3. **parallelism** (parallel lines remain parallel)
4. **collinearity** (points remain on the same lines)
5. **orientation** (lettering order remains the same)

★ **Dilation** → a transformation that produces an image that is the same shape as the original, but is a different size



★ **NOT** an isometry, but orientation IS preserved

Directions: Fill in the chart with the coordinates of the image after each transformation. Then write the transformations as a composition of transformations. **MAKE SURE TO LABEL WITH PRIMES!**

Ex: Reflect over the y-axis. Rotate 180°. Translate $(x,y) \rightarrow (x-3, y+1) \rightarrow T_{-3,1} \circ R_{0,180^\circ} \circ r_{y\text{-axis}}$

1. Pre-image: A(0,0), B(8,1), C(5,5)

Rotate the figure 180°	A'(0,0) B'(-8,-1) C'(-5,-5)
Reflect the figure over the x-axis	A''(0,0) B''(-8,1) C''(-5,5)
Translate the figure according to $(x,y) \rightarrow (x+6,y-1)$	A'''(6,-1) B'''(-2,0) C'''(1,4)
Composition of transformations	$T_{(6,-1)} \circ r_{x\text{-axis}} \circ R_{0,180^\circ}$